



# higher education & training

Department:  
Higher Education and Training  
**REPUBLIC OF SOUTH AFRICA**

## **MARKING GUIDELINE**

### **NATIONAL CERTIFICATE MECHANOTECHNICS N6**

**30 JULY 2018**

This marking guideline consists of 7 pages.

**QUESTION 1**

$$\begin{aligned}
 1.1 \quad P &= \frac{2\pi NT}{60} \\
 &= \frac{2 \times \pi \times 1500 \times 142}{60} \checkmark \\
 &= 22,3 \text{ kW} \checkmark
 \end{aligned} \tag{2}$$

$$\begin{aligned}
 1.2 \quad T &= \mu \times F_A \times R_m \times n \\
 F_A &= \frac{T}{\pi \times R_m \times n} \checkmark \\
 &= \frac{142 \times 2}{0,3 \times 0,095 \times 2} \checkmark \\
 &= 4982 \text{ N} \checkmark
 \end{aligned} \tag{3}$$

$$\begin{aligned}
 1.3 \quad I &= mk^2 \\
 I_m &= 63,5 \times 0,14^2 = 1,245 \text{ kgm}^2 \checkmark \\
 I_r &= 22,8 \times 0,075^2 = 0,128 \text{ kgm}^2 \checkmark \\
 (I_m + I_r)N_3 &= I_m N_m + I_r N_r \checkmark \\
 \therefore 1,373 N_3 &= 0 + 0,128 \times 1500 \checkmark \\
 N_3 &= 139,8 \text{ r/min} \checkmark
 \end{aligned} \tag{5}$$

$$\begin{aligned}
 1.4 \quad \omega_1 &= \frac{2\pi \times 1500}{60} = 157 \text{ rad/s} \checkmark \\
 \omega_2 &= \frac{2\pi \times 139,8}{60} = 14,6 \text{ rad/s} \checkmark \\
 T &= I\alpha \qquad \qquad \qquad \text{OR} \\
 \alpha_m &= \frac{142}{1,245} = 114 \text{ rad/s}^2 \checkmark & \alpha_r &= \frac{142}{0,128} = 1109 \text{ rad/s}^2 \checkmark \\
 t &= \frac{\omega_1 - \omega_2}{\alpha} & t &= \frac{\omega_2 - \omega_1}{\alpha} \\
 &= \frac{14,6 - 0}{114} = 0,128 \text{ sec} \checkmark & &= \frac{157 - 14,6}{1109} = 0,128 \text{ sec} \checkmark
 \end{aligned} \tag{4}$$

$$\begin{aligned}
 1.5 \quad E_{kloss} &= E_{kin} - E_{kf} \\
 &= \frac{1}{2} I_1 \omega_1^2 + \frac{1}{2} I_2 \omega_2^2 - \frac{1}{2} (I_1 + I_2) \omega_3^2 \checkmark \\
 &= \frac{1}{2} (0,128)(157)^2 + 0 - \frac{1}{2} (0,128 + 1,245)(14,6)^2 \checkmark \\
 &= 1431 \text{ J} \checkmark
 \end{aligned} \tag{3}$$

[17]

**QUESTION 2**

2.1       $v = \frac{\pi \times 0,85 \times 510}{60} = 22,698 \text{ m/s} \checkmark$   
 $P = (T_1 - T_2) \times v \quad \frac{T_1}{T_2} = e^{\mu\theta}$   
 $25\ 000 = (T_1 - T_2) \times 22,698 \quad = e^{0,27\pi}$   
 $(T_1 - T_2) = 1\ 101,4 \text{ N} \checkmark \quad = 2,335 \checkmark$   
 $1,335 T_2 = 2\ 220 \text{ N} \checkmark$   
 $T_2 = 825 \text{ N} \quad \text{and} \quad T_1 = 1\ 926 \text{ N} \checkmark$

(5)

2.2       $T_s = (T_1 - T_2) \times r$   
 $= (1\ 962 - 825) \times 0,425 \checkmark$   
 $= 467,9 \text{ Nm} \checkmark$

(2)

2.3       $T_p = \frac{T_s \times N_s}{N_p}$   
 $= \frac{467,9 \times 510}{10\ 200}$   
 $= 198,86 \text{ N} \checkmark$

(1)

2.4       $F_t = \frac{T \times 2}{PCD}$   
 $= \frac{198,86 \times 2}{0,1} \checkmark$   
 $= 3\ 977,2 \checkmark$

(2)

2.5       $F_n = F_t \sec \theta$   
 $= 3\ 977,2 \sec 20^\circ \checkmark$   
 $= 4\ 232,4 \text{ N} \checkmark$

(2)

2.6       $\sum \curvearrowright M = \sum \curvearrowleft M \text{ About/Om } L$   
 $R \times 1,75 = (T_1 + T_2 + m \times g) \times 0,5 \checkmark$   
 $R \times 1,75 = (1\ 926 + 825 + 90 \times 9,81) \times 0,5 \checkmark$   
 $R = 1\ 038 \text{ N} \checkmark$   
 $L + R = T_1 + T_2 + m \times g \checkmark$   
 $L + 1\ 038 = 1\ 926 + 825 + 90 \times 9,81 \checkmark$   
 $L = 2\ 595 \text{ N} \checkmark$

(6)  
[18]

**QUESTION 3**

3.1      3.1.1       $WD = F \times s$

$$= 23\ 000 \times 9,81 \times 0,03 \times 100 / 75 \checkmark$$

$$= 9\ 025 J = \Delta E_k \checkmark$$

$$\omega = \frac{2\pi N}{60}$$

$$\omega_1 = \frac{2\pi \times 296}{60}$$

$$= 31 \text{ rad/s}$$

$$\omega_2 = \frac{2\pi \times 248}{60}$$

$$= 26 \text{ rad/s} \checkmark$$

$$\Delta E_k = E_{k1} - E_{k2}$$

$$= \frac{1}{2} I (\omega_1^2 - \omega_2^2)$$

$$9\ 025 = \frac{1}{2} \times 9\ 025 (31^2 - 26^2) \checkmark$$

$$\therefore I = 63,33 \text{ kgm}^2 \checkmark$$

(5)

3.1.2       $P = \frac{WD}{t}$

$$= \frac{9\ 025 \times 10}{60} \checkmark$$

$$= 1\ 504 W \checkmark$$

(2)

3.2       $\frac{T_1}{T_2} = e^{\mu\theta}$        $T_2 = 250 \text{ N}$

$$= e^{0,3 \times 225 \div 57,3} \checkmark$$

$$= 3,248 \checkmark$$

$$\therefore T_1 = 3,248 \times 250 \checkmark$$

$$= 812 \text{ N} \checkmark$$

$$T_b = (T_1 - T_2) \times R$$

$$T_b = (812 - 250) \times 0,2 \checkmark$$

$$= 112,4 \text{ Nm} \checkmark$$

(6)  
[13]

**QUESTION 4**

4.1       $I = mk^2$

$$I = 80 \times 0,2^2 \checkmark$$

$$= 3,2 \text{ kgm}^2 \checkmark$$

(2)

4.2       $T_D = T_A \times VR$

$$= \frac{3,5 \times 52 \times 55}{25 \times 30} \checkmark$$

$$= 13,35 \text{ Nm} \checkmark$$

$$I_{D \text{ total}} = I_A \times VR^2 + (I_B + I_C) \times VR^2 + I_D + I_{drum} \checkmark \checkmark$$

$$= 0,23 \times \left( \frac{52 \times 55}{25 \times 30} \right)^2 \checkmark + (0,75 + 0,3) \times \left( \frac{55}{30} \right)^2 \checkmark + 1,2 + 3,2 \checkmark \checkmark$$

$$= 11,27 \text{ kgm}^2 \checkmark \checkmark$$

$$T = I\alpha$$

$$\alpha = 13,35 \div 11,27 \checkmark$$

$$= 1,185 \text{ rad/s}^2 \checkmark$$

(14)  
[16]**QUESTION 5**

5.1      Maximum skidding speed:

$$v = \sqrt{gr \left( \frac{\mu + \tan \theta}{1 - \mu \tan \theta} \right)}$$

$$= \sqrt{9,81 \times 130 \left( \frac{0,6 + \tan 20^\circ}{1 - 0,6 \tan 20^\circ} \right)} \checkmark$$

$$v = 39,65 \text{ m/s}$$

$$= 142,77 \text{ km/h} \checkmark$$

Maximum overturning speed:

$$v = \sqrt{gr \left( \frac{htan\theta + \frac{b}{2}}{h - \frac{b}{2}tan\theta} \right)}$$

$$= \sqrt{9,81 \times 130 \left( \frac{0,65tan20^\circ + \frac{1,5}{2}}{0,65 - \frac{1,5}{2}tan20^\circ} \right)} \checkmark$$

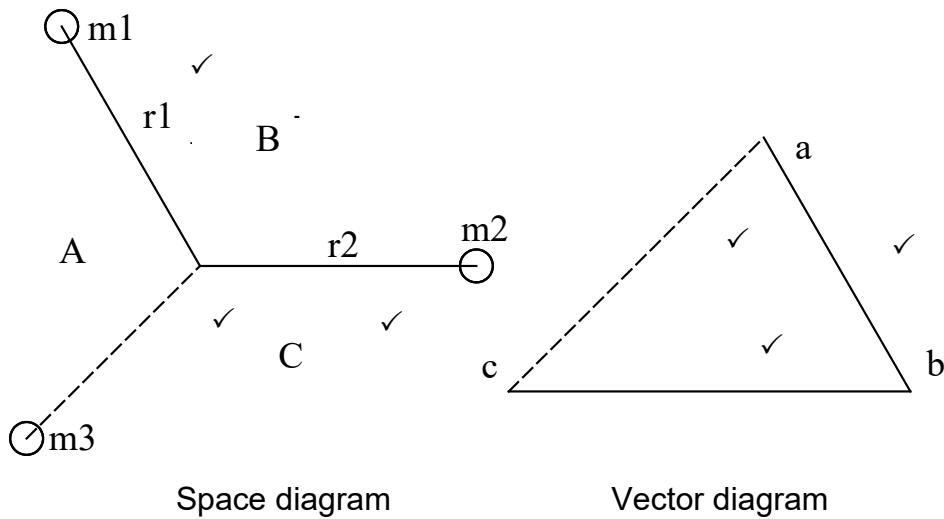
$$v = 57,77 \text{ m/s}$$

$$= 207,9 \text{ km/h} \checkmark$$

The maximum safe speed is 142,77 km/h to prevent skidding.  $\checkmark \checkmark$

(6)

5.2       $m_1 r_1 = 114,5 \times 91 = 1\,312 \text{ kg.mm}\checkmark$   
 $m_2 r_2 = 17,91 \times 101 = 1\,809 \text{ kg.mm}\checkmark$



$$m_3 r_3 = 54 \times 30 \checkmark$$

$$= 1\,620 \checkmark$$

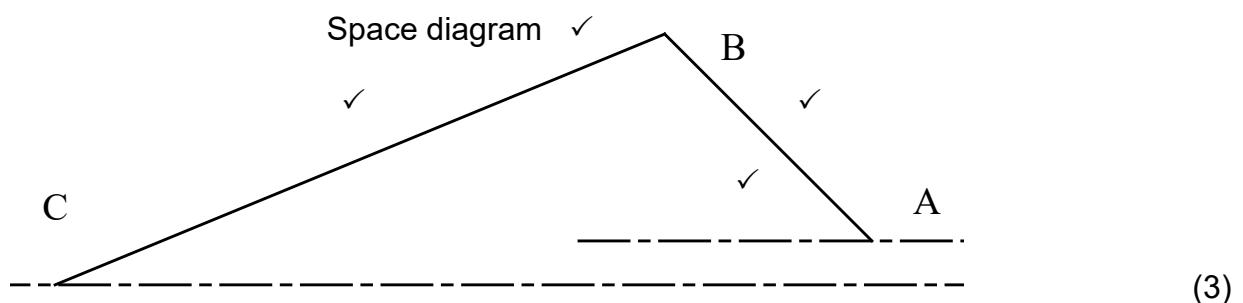
$$r = \frac{1\,620}{15} \checkmark$$

$$= 108 \text{ mm}\checkmark$$

(12)  
[18]

## QUESTION 6

6.1



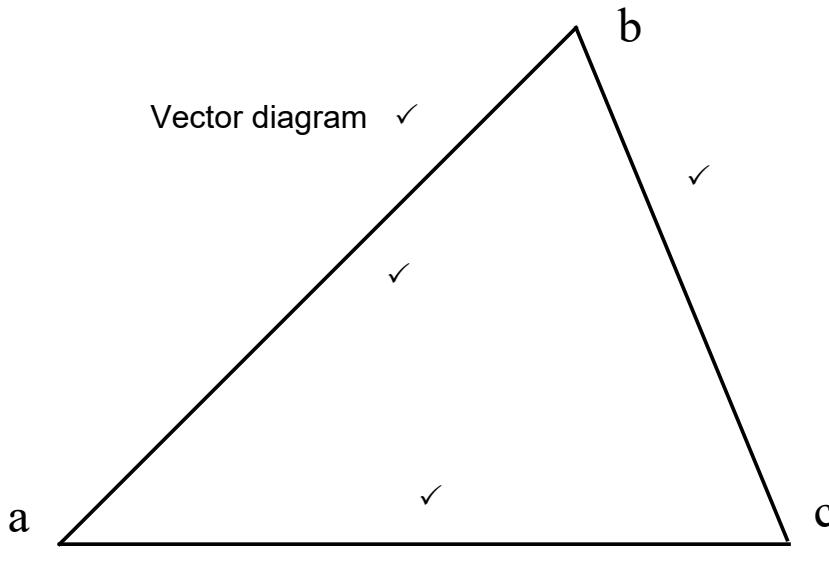
6.2       $v_b = \frac{2\pi r N}{60}$

$$= \frac{2\pi \times 0,2 \times 150}{60} \checkmark$$

$$= 3,14 \text{ m/s}\checkmark$$

(2)

6.3



(3)

6.4      6.4.1       $v_c = ac \times 0,04$   
 $= 78,4 \times 0,04$   
 $= 3,136 \text{ m/s}$       (3)

6.4.2       $\omega_{BC} = \frac{v_{BC}}{BC}$   
 $= \frac{60 \times 0,04}{0,45} \checkmark$   
 $= 5,33 \text{ rad/s} \checkmark$

In an anticlockwise direction at  $67,6^\circ$  to the horizontal ✓      (3)

6.4.3       $a_{B \text{ rel to } C} = \frac{v_{BC}^2}{BC}$   
 $= \frac{(60 \times 0,04)^2}{0,45} \checkmark$   
 $= 12,8 \text{ m/s}^2 \checkmark$       (2)

6.4.4       $a_{B \text{ rel to } A} = \frac{v_{BA}^2}{AB}$   
 $= \frac{(3,14)^2}{0,2} \checkmark$   
 $= 49,298 \text{ m/s}^2 \checkmark$       (2)  
**[18]**

**TOTAL:**      **100**