



**higher education
& training**

Department:
Higher Education and Training
REPUBLIC OF SOUTH AFRICA

MARKING GUIDELINE

NATIONAL CERTIFICATE

CONTROL SYSTEMS N6

8 AUGUST 2018

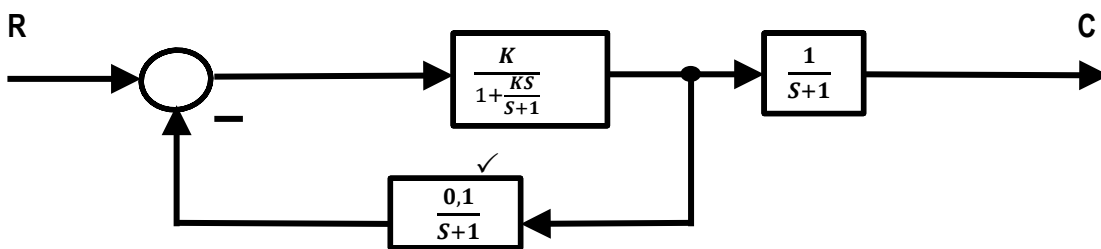
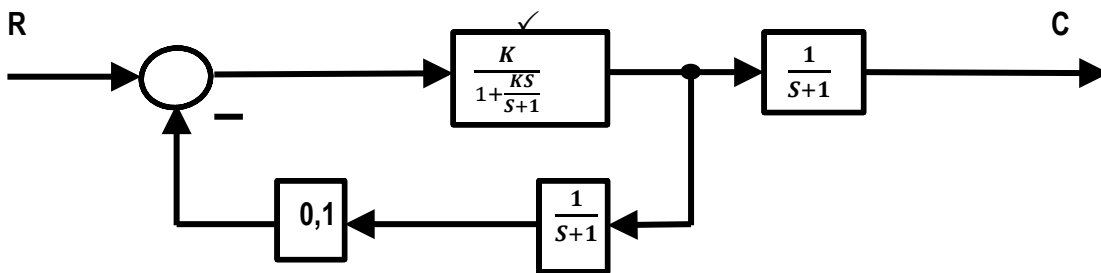
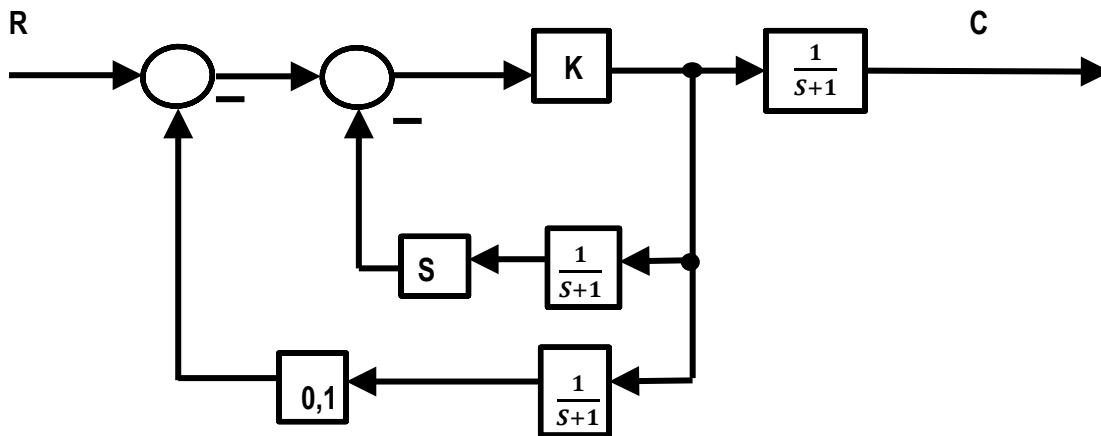
This marking guideline consists of 9 pages.

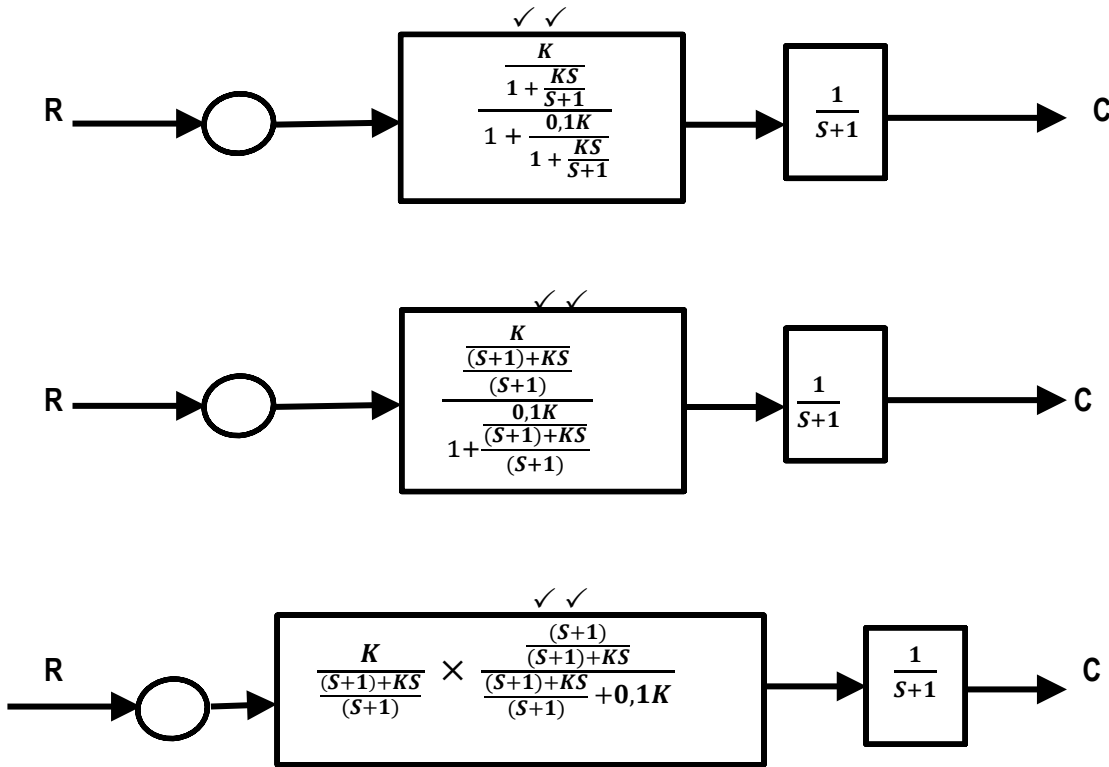
QUESTION 1

- 1.1 True
- 1.2 False
- 1.3 False
- 1.4 True
- 1.5 True
- 1.6 False
- 1.7 True
- 1.8 False
- 1.9 False
- 1.10 True

(10 × 1) [10]

QUESTION 2





$$\frac{C}{R} = \frac{K}{\frac{(s+1)+KS}{(s+1)} + 0,1K} \times \frac{1}{(s+1)} \checkmark$$

$$\frac{C}{R} = \frac{K}{s+1 + KS + 0,1K} \checkmark$$

[10]

QUESTION 3

- 3.1 3.1.1 20,5 dB (1)
- 3.1.2 66 rad/s (1)
- 3.1.3 75 rad/s (1)
- 3.1.4 21,5 dB/decade or 10 dB/octave (1)
- 3.1.5 1,25 dB (below unity therefore positive) (1)
- 3.1.6 $180^\circ - 178,5^\circ = 1,5^\circ$ (1)
- 3.1.7 The system is stable because the gain response is below unity when the phase is -180° and the phase is shy of -180° when the gain is in unity. (2)

- 3.2 A system is considered unstable when the gain and phase margins have negative values because they exceed the unity and 180° respectively. (2)
[10]

QUESTION 4

- 4.1 4.1.1 6,3 dB (1)
 4.1.2 21° (1)
 4.1.3 5,2 rad/sec (1)
 4.1.4 7,4 rad/sec (1)
 4.1.5 5,3 rad/sec (1)
 4.1.6 5,4 rad/sec (1)
 4.1.7 10 dB and -103° (2)
 4.1.8 8,3 rad/sec (1)
- 4.2 Stable (1)
[10]

QUESTION 5

- 5.1 The denominator = $S^2 + 4S + 20A$

$$S = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

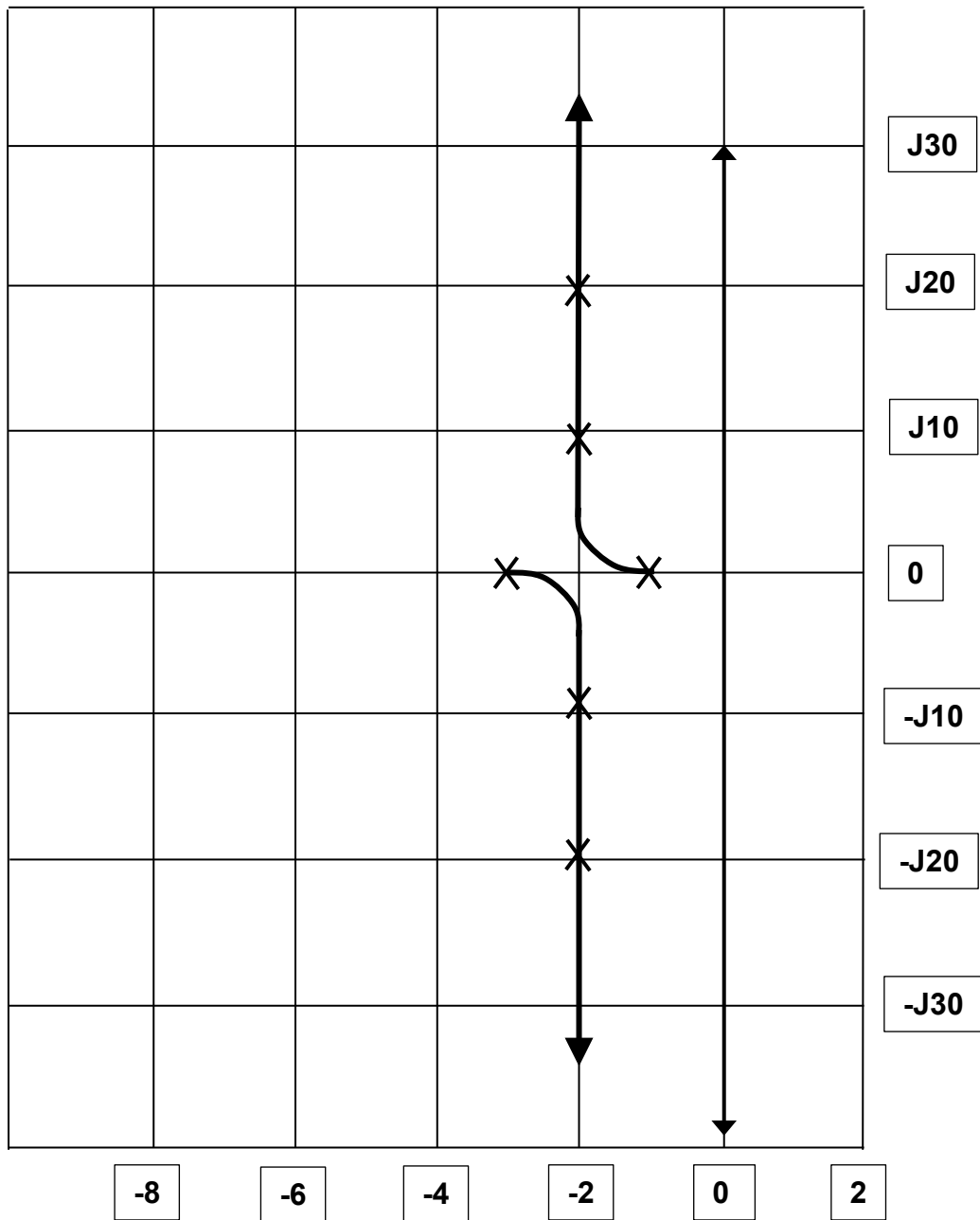
$$= \frac{-(4) \pm \sqrt{2^2 - 4(1)(20A)}}{2(1)}$$

$$= -2 \pm \frac{\sqrt{4 - 80A}}{2} \checkmark$$

		✓	✓	✓	✓
A	0	4	20	∞	
S ₁	-1	-2+j8,889	-2+j19,975	-2+j∞	
S ₂	-3	-2-j8,889	-2-j19,975	-2-j∞	

(5)

5.2



(5)
[10]

QUESTION 6

$$\frac{\theta(s)}{Ta(s)} = \frac{1}{0,15s^2 + 0,5s + 1} = \frac{A\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$6.1 \quad \begin{aligned} \omega_n^2 &= 1 \\ \omega_n &= \sqrt{1} \checkmark \\ \omega_n &= 1 \text{ rad/s} \checkmark \end{aligned} \quad (2)$$

$$6.2 \quad \begin{aligned} 2\zeta\omega_n &= 0,5 \\ \zeta &= \frac{0,5}{2 \times 1} \checkmark \\ \zeta &= 0,25 \checkmark \end{aligned} \quad (2)$$

$$6.3 \quad \begin{aligned} \omega_d &= \omega_n \sqrt{1 - \zeta^2} \\ \omega_d &= 1 \sqrt{1 - 0,25^2} \checkmark \\ \omega_d &= 0,968 \text{ rad/s} \checkmark \end{aligned} \quad (2)$$

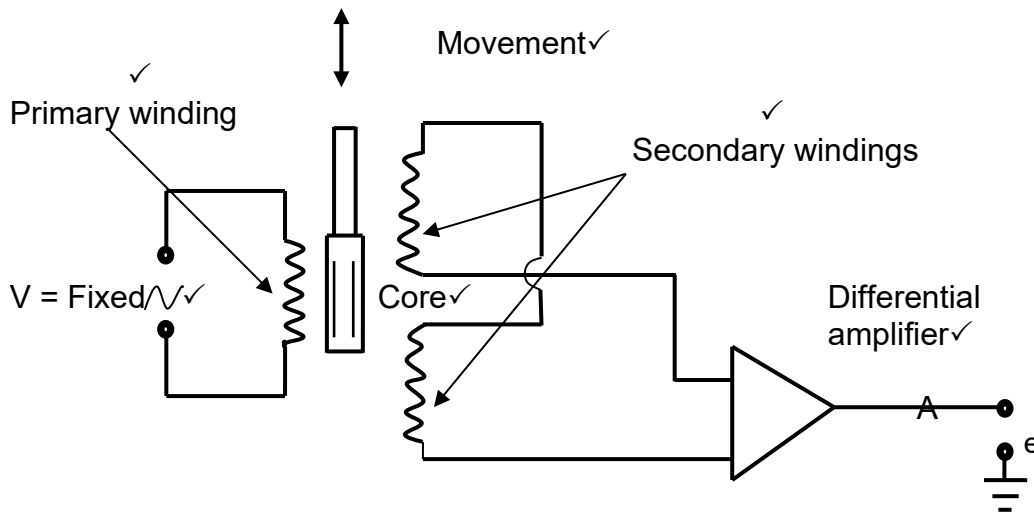
$$6.4 \quad \begin{aligned} \omega_b &= \omega_n \sqrt{1 - \zeta^2 + \sqrt{2 - 4\zeta^2 + 4\zeta^4}} \\ \omega_b &= 1 \sqrt{1 - 0,25^2 + \sqrt{2 - (4 \times 0,25^2) + (4 \times 0,25^4)}} \checkmark \checkmark \\ \omega_b &= 1,5 \text{ rad/s} \checkmark \end{aligned} \quad (3)$$

$$6.5 \quad \begin{aligned} \alpha &= \zeta\omega_n \\ \alpha &= 0,25 \times 1 \\ \alpha &= 0,25 \checkmark \end{aligned} \quad (1)$$

[10]

QUESTION 7

7.1



(6)

7.2

- It has a primary winding with a fixed AC voltage and two secondary windings opposing each other. A movable magnetic core couples the windings.
- When the core is entered, the voltage of both the secondary windings is the same due to the flux path being identical and the output voltage is zero.
- As the core moves up or down the magnetic coupling causes an increase in induced voltage in either the top or bottom secondary winding.
- The output voltage is proportional to the displacement with a phase relationship depending on the direction of displacement.

(4)

[10]

QUESTION 8

8.1

- Radial-action piston pump
- Axial piston-type pump

(2)

8.2

8.2.1 Vane-type pump

(1)

8.2.2 A – Inlet port
B – Outlet port
C – Vane/Blade

(3)

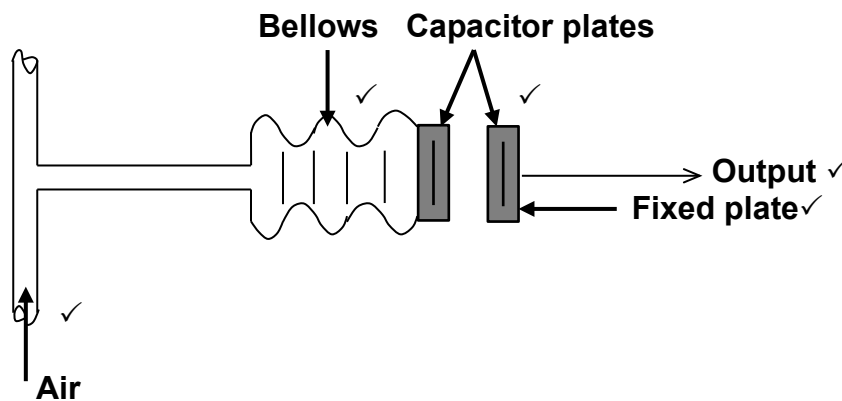
- 8.2.3
- As the rotor turns, a vacuum is created at the inlet side of the pump and fluid is sucked in.
 - The sliding vanes which slide in the rotor move outwards due to a centrifugal force.
 - The centrifugal force and pressure keeps the vanes in contact with the casing as the vanes move the fluid along the cavity of the pump in the direction of rotation.
 - At the outlet, the cavity gets smaller and pressure increases causing the fluid to be exited with a force.

(4)
[10]

QUESTION 9

9.1 It cannot be used alone because it will not respond to a steady-state error. (2)

9.2



(5)

- 9.3
- Steady state is a condition where the input signal is a constant value and the output has stabilised by levelling out at a constant value or reaching a constant rate of change.
 - Steady state is a condition when the input signal is a constant amplitude cycle such as a sine wave and the output signal has also become a constant amplitude cycle.

(Any 1 × 3)

(3)
[10]

QUESTION 10

- 10.1 • Analog voltmeters
 • Digital voltmeters (2)
- 10.2 10.2.1 Pulse repetition frequency is the number of pulses produced per second.
- 10.2.2 Mark-to-space ratio is the ratio of the width of the pulse to the time between pulses. (2 × 2) (4)
- 10.3 • Cathode-ray tube
 • Time-base generator
 • Amplifiers
 • Attenuator
 • Power supplies (Any 4 × 1) (4)
- [10]**
- TOTAL: 100**