



**higher education  
& training**

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Department:  
Higher Education and Training  
**REPUBLIC OF SOUTH AFRICA**

# **MARKING GUIDELINE**

**NATIONAL CERTIFICATE  
NOVEMBER EXAMINATION  
ELECTRO-TECHNOLOGY N3**

**23 NOVEMBER 2016**

**This marking guideline consists of 7 pages.**

**QUESTION 1**

- 1.1 1.1.1 Commutation – is the reversal of the EMF and current✓ to the short-circuited coil✓ during its transfer from one commutator segment to the next.✓ (3)
- 1.1.2 Pole pitch – is the angular distance between the centre of two adjacent poles. ✓ (1)

1.2

(4 marks for 4 labels. 2 marks for correct sketch) (6)

[10]

**QUESTION 2**

- 2.1
- Damaging brushes OR the commutator surface.
  - To short circuit by formation of an arc.
- (2)
- 2.2 Short compound motor – is when a series field coil is connected in series✓with a parallel connection of a shunt field coil and armature. ✓ (2)
- 2.3 2.3.1 Motor commutation – is to provide a difference in polarity between the armature and the field in order to produce motion. (1)
- 2.3.2 Generator commutation – is to produce a steady voltage which remains constant. (1)
- 2.4 Given:  $P = 4$ ;  $C = 2$ ;  $\Phi = 40 \text{ mWb} = 0,04 \text{ Wb}$ ;  $N = 14 \text{ r/sec}$ ;  $E = 120 \text{ V}$   
Total number of conductors in armature =?

$$E = \frac{2p\Phi ZN}{60C}$$

$$Z = \frac{E \times 60C}{2p\Phi N}$$

$$= \frac{120V \times 2}{2 \times 4 \times 0,04 \times 14} \checkmark \checkmark$$

$$= 53,571 \checkmark \checkmark \text{ or } 54 \text{ conductors} \longrightarrow \text{Answer} \quad (4)$$

[10]

**QUESTION 3**

- 3.1
- Friction loss
  - Wind loss
  - Iron loss
- (Any 2 x 1) (2)

- 3.2
- Speed [N]
  - Flux [ $\Phi$ ]
- (2)

3.3 3.3.1

$$\begin{aligned} \text{Flux } [\Phi] &= \frac{T \times c}{0,318 \times Z \times p \times I_a} \\ &= \frac{980 \times 2 \times 4}{0,318 \times 660 \times 4 \times 400} \checkmark \checkmark \\ &= 0,023 \text{ Wb OR } 23,346 \text{ mWb} \checkmark \longrightarrow \text{Answer} \end{aligned} \quad (3)$$

3.3.2

$$\begin{aligned} \text{Flux } [\Phi] &= \frac{T \times c}{0,318 \times Z \times p \times I_a} \\ &= \frac{980 \times 2}{0,318 \times 660 \times 4 \times 400} \checkmark \checkmark \\ &= 0,00584 \text{ Wb OR } 5,836 \text{ mWb} \checkmark \longrightarrow \text{Answer} \end{aligned} \quad (3)$$

**[10]**

**QUESTION 4**

- 4.1 4.1.1 When the current reaches overload magnitude, ✓ the heating coil will heat the bimetal strip ✓ to the extent that it will bend far enough ✓ to operate the tripping contacts. ✓ (4)

- 4.1.2 By the time taken for the bi-metal strip to bend. (1)

- 4.2 4.2.1 Oil
- 4.2.2 Overload coil
- 4.2.3 Oil dashpot
- 4.2.4 Piston
- 4.2.5 Plunger
- (5)  
**[10]**

**QUESTION 5**

5.1 5.1.1 Current through Resistor  $[I_R] = \frac{210V}{70\Omega}$   
 $= 3A \checkmark \longrightarrow$  Answer (1)

5.1.2 Current through Capacitor  $\{I_C\} = 210V \times 2 \times 3,142 \times 60 \times 130 \times 10^{-6} \checkmark$   
 $= 10,293A \checkmark \longrightarrow$  Answer (2)

5.1.3 Current through Inductor  $[I_L] = \frac{210V}{2 \times 3,142 \times 60 \times 0,04} \checkmark$   
 $= 13,924A \checkmark \longrightarrow$  Answer (2)

5.2 5.2.1  $Z = \sqrt{R^2 + (X_C - X_L)^2} = \sqrt{70^2 + (20.402 - 15.082)^2} \checkmark \checkmark$   
 $= 70,202\Omega \checkmark \longrightarrow$  Answer (3)

5.2.2  $I_t = \frac{V_t}{Z} = \frac{210V}{70,202\Omega} \checkmark$   
 $= 2,991A \checkmark \longrightarrow$  Answer (2)

**[10]****QUESTION 6**

6.1 The virtual value  $= \sqrt{\frac{i_1^2 + i_2^2 + i_3^2 + \dots + i_n^2}{n}}$  amps  
 $= \sqrt{\frac{10^2 + 20^2 + 36^2 + 38^2 + 28^2 + 14^2}{6}} \checkmark$   
 $= \sqrt{\frac{100 + 400 + 1296 + 1444 + 784 + 196}{6}} \checkmark$   
 $= \sqrt{703,333} \checkmark$   
 $= 26,520A \checkmark \longrightarrow$  Answer (4)

6.2 The average value  $= \frac{i_1 + i_2 + i_3 + \dots + i_n}{n}$   
 $= \frac{10A + 20A + 36A + 38A + 28A + 14A}{6} \checkmark$   
 $= \frac{146}{6} \checkmark$   
 $= 24,333A \checkmark \longrightarrow$  Answer (3)

6.3 The form factor  $= \frac{I_{rms}}{I_{ave}}$   
 $= \frac{26,520A}{24,333A}$   
 $= 1,089 \checkmark \longrightarrow$  Answer (1)

6.4 The crest factor =  $\frac{I_m}{I_{rms}}$   
 $= \frac{40}{26,520}$   
 $= 1,508 \checkmark \longrightarrow$  Answer (1)

6.5 Peak wave or sine wave or sinusoidal wave.  $\checkmark$  (1)  
**[10]**

### QUESTION 7

7.1 Power = VI  
 Current =  $\frac{70}{140} \checkmark$   
 $= 0,5 \text{ A} \checkmark \longrightarrow$  Answer (2)

7.2 Voltage = IR  
 Resistance =  $\frac{140}{0,5} \checkmark$   
 $= 280 \Omega \checkmark \longrightarrow$  Answer (2)

7.3 Impedance (Z) =  $\frac{\text{Voltage}}{\text{Current}}$   
 $= \frac{200 \text{ V}}{0,5 \text{ A}} \checkmark$   
 $= 400 \Omega \checkmark \longrightarrow$  Answer (2)

7.4 The inductance value of the circuit (L) = ?  
 $Z = \sqrt{R^2 + X_L^2}$   
 $X_L = \sqrt{400^2 - 280^2} \checkmark$   
 $= 285,657 \Omega \checkmark \longrightarrow$   
 $X_L = 2\pi fL$   
 $L = \frac{285,657 \Omega}{2 \times 3,142 \times 60} \checkmark$   
 $= 0,758 \text{ H or } 758 \text{ mH} \checkmark \longrightarrow$  Answer (4)  
**[10]**

**QUESTION 8**

- 8.1
- It delivers higher power.
  - It generates a higher torque.
  - A three-phase supply is more versatile when connected in star ( $V_L$  and  $V_{PH}$ ).
  - In the case of alternators, the same size prime mover is required for both single and three-phase. (Any 3 x 1) (3)
- 8.2
- 8.2.1 The apparent power [S] =  $\sqrt{3} VI$   
 $= \sqrt{3} \times 380 \text{ V} \times 9 \text{ A}$   
 $= 5\,923,613 \text{ VA} \checkmark$   
 $= 5,924 \text{ kVA} \checkmark \longrightarrow \text{Answer}$  (2)
- 8.2.2 The actual power [P] =  $\sqrt{3} \times V_L \times I_L \times \cos \theta$   
 $= \sqrt{3} \times 380 \times 9 \times 0,85 \checkmark$   
 $= 5\,035,072 \text{ W} \checkmark$   
 $= 5,035 \text{ kW} \checkmark \longrightarrow \text{Answer}$  (3)
- 8.2.3 The phase current of the motor winding [ $I_{ph}$ ] =  $\frac{I_L}{\sqrt{3}}$  Delta connection  
 $= \frac{9 \text{ A}}{\sqrt{3}} \checkmark$   
 $= 5,196 \text{ A} \checkmark \longrightarrow \text{Answer}$  (2)
- [10]**

**QUESTION 9**

- 9.1
- | Moving-iron Instrument | Dynamo-meter Instrument |
|------------------------|-------------------------|
| • Uneven scale         | • Uneven scale          |
| • Pointer/Needle       | • Pointer/Needle        |
| • Balance weight       | • Balance weight        |
| • Spring               | • Spring                |
- (4)
- 9.2
- 9.2.1 As a voltmeter:
- $$R_t = \frac{V_t}{I_t} = \frac{6\text{V}}{0,006\text{A}}$$
- $$= 1\,000 \, \Omega \longrightarrow \text{Answer} \checkmark$$
- $$R_{series} = R_t - R_m$$
- $$= 1\,000 \, \Omega - 120 \, \Omega \checkmark$$
- $$= 880 \, \Omega \longrightarrow \text{Answer} \checkmark$$
- (3)

9.2.2 As an ammeter:  
Voltage across ammeter  

$$V_m = I_m R_m = 0,006 A \times 120 \Omega$$

$$= 0,72 V \rightarrow \text{Answer} \checkmark$$
 Current through shunt  

$$I_s = I_t - I_m = 2 A - 0,006 A$$

$$= 1,994 A \rightarrow \text{Answer} \checkmark$$

$$R_s = \frac{V_s}{I_s} = \frac{0,72 V}{1,994 A}$$

$$= 0,361 \Omega \rightarrow \text{Answer} \checkmark$$

(3)  
[10]**QUESTION 10**

10.1	10.1.1	5 valence electrons	(2)
	10.1.2	3 valence electrons	(2)
10.2	Capacitor		(1)
10.3	Motor-speed control; time-delay circuits; battery charger; heater control; relay circuit; regulated power supplies; static switches; phase controls		(5)
		(Any 5 x 1)	[10]

**TOTAL: 100**