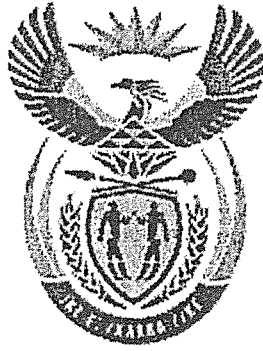


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Department:
Higher Education and Training
REPUBLIC OF SOUTH AFRICA

T520(E)(M25)T
APRIL EXAMINATION

NATIONAL CERTIFICATE

ELECTROTECHNICS N5

(8080085)

25 March 2013 (X-Paper)
09:00–12:00

Calculators may be used.

This question paper consists of 5 pages and a 2-page formula sheet.

DEPARTMENT OF HIGHER EDUCATION AND TRAINING
REPUBLIC OF SOUTH AFRICA
NATIONAL CERTIFICATE
ELECTROTECHNICS N5
TIME: 3 HOURS
MARKS: 100

INSTRUCTIONS AND INFORMATION

1. Answer ALL the questions.
 2. Read ALL the questions carefully.
 3. Number the answers according to the numbering system used in this question paper.
 4. Write neatly and legibly.
-

QUESTION 1

- 1.1 Briefly explain the term *commutation*. (2)
- 1.2 What is meant by *armature reaction*? (2)
- 1.3 The armature resistance of a six-pole, 500 V wave connected series motor is $0,5 \Omega$, which takes 61 amperes from the supply. The motor has 72 slots with 10 conductors in each slot. The total flux per pole is 50 mWb. Calculate the speed of the motor. (6)
- 1.4 A 40 kW, 500 V, DC shunt motor has an armature resistance of $0,35 \Omega$. The full-load armature current is 100 A. What resistance should be inserted in series in the armature circuit to obtain a 20% speed reduction and a decrease of 20% of the rated torque?
The flux remains constant. (6)
- 1.5 A 55 kW, 650 V, DC shunt motor has a speed of 1 800 r/min and the full load efficiency is 85%. The armature circuit resistance is 0,3 ohms and the total voltage drop is 2,5 V at the brushes. The field current is 3 A.

Calculate:

- 1.5.1 The full-load line current (2)
- 1.5.2 The full-load shaft torque in N.m (4)
- [22]

QUESTION 2

- 2.1 Sketch the phasor diagram for a series circuit at resonance. (3)
- 2.2 The following ordinates were taken during a half cycle of a symmetrical alternating current wave. The current varying in a linear manner between successive points:

Phase angle in degrees	0	30	60	90	120	150	180
Current in amperes	0	10,1	22,4	30	27	22,4	0

Without plotting the graph, determine the following:

- 2.2.1 The mean value (6)
- 2.2.2 The RMS value (2)

- 2.3 A coil with a resistance of 10Ω and an inductance of $0,0191 \text{ H}$ is connected in parallel with a circuit with a $75 \mu\text{F}$ capacitor in series with a 5Ω resistance. The circuit is connected to a 120 V , 50 Hz supply.

Determine:

- 2.3.1 The current in each branch (3)
- 2.3.2 The total supply current, power factor and power (4)
- [18]

QUESTION 3

- 3.1 3.1.1 Explain how iron losses are affected when the frequency of a transformer is changed. (1)
- 3.1.2 Name ONE method that can be used to minimise eddy current losses in a transformer. (1)
- 3.1.3 List THREE methods of reducing leakage flux in transformers. (3)
- 3.2 If one transformer is too small, then we can connect a second transformer in parallel to the first one. Name FOUR requirements necessary before the two transformers can be connected in parallel. (4)
- 3.3 A 12 kVA , 2 500/500 V single-phase transformer, operating at no-load, has resistances and leakage reactance as follows:
- Primary winding: Resistance $8,5 \Omega$, reactance 15Ω
Secondary winding: Resistance $0,5 \Omega$, reactance $0,9 \Omega$
- Determine the approximate value of the secondary voltage at full-load, with a power factor of $0,85$ (lagging), when the primary supply voltage is 2 500 V . (6)
- 3.4 A three-phase, 660 V , star-connected motor has an output of 85 kW , with an efficiency of 90% and a power factor of $0,8$.
- Calculate:
- 3.4.1 The line current (3)
- 3.4.2 If the motor windings were connected in delta, what would be the three-phase voltage supply suitable for the motor? (2)
- [20]

QUESTION 4

- 4.1 Name THREE conditions to be met when connecting alternators in parallel to busbars. (3)
- 4.2 Explain the term *hunting* with reference to synchronous motors. (3)
- 4.3 Explain the term *distribution factor* (k_d). (3)
- 4.4 TWO wattmeters are used to measure the input power to a balanced three-phase load, which has a unity power factor. EACH meter indicates 17,5 kW. The power factor drops to 0,8 lagging but the power remains unchanged. (8)
- Calculate the readings on the wattmeters.
- 4.5 THREE identical coils are connected in star across a three-phase, 370 V, 50 Hz supply. The readings on TWO wattmeters connected to measure the total power are 2,5 kW and 1,8 kW respectively.
- Calculate:
- 4.5.1 The power factor (3)
- 4.5.2 The line current (2)
- [22]

QUESTION 5

- 5.1 A three-phase induction motor has 8 poles and is supplied from a 50 Hz supply.
- Calculate:
- 5.1.1 The synchronous speed (3)
- 5.1.2 The rotor speed when the slip is 8% (3)
- 5.1.3 The rotor frequency when the rotor runs at 250 r/min (2)
- 5.2 TWO similar single-phase alternators are connected in parallel. Each machine has a synchronous impedance of $0,9 + j10,5$ ohms. When excited, an open circuit EMF of 2 300 V is generated. The machines have a phase displacement of 40 electrical degrees relative to each other.
- Calculate:
- 5.2.1 The circulating current (6)
- 5.2.2 The terminal voltage (2)
- 5.2.3 The power supplied from one machine to the other (Assume that there is no external load.) (2)
- [18]
- TOTAL: 100

ELECTROTECHNICS N5

FORMULA SHEET

Armature ampere-turns/pole

$$= \frac{1}{2} \cdot \frac{I_a}{C} \cdot \frac{Z}{2P}$$

$$E = V \pm I_a R_a$$

$$E = \frac{2pNZ\Phi}{60c}$$

$$T = 0,318 \frac{I_a}{c} ZP\Phi$$

$$k = n \sqrt{\frac{R_1}{r_m}}$$

$$r_1 = R_1 \left[\frac{k-1}{k} \right]$$

$$r_1 = R_s \frac{1-y}{1-y^m}$$

$$R_1 = bR_1 (k-1) \times \frac{1-b^n}{1-b} + r_m$$

$$y = \frac{I_2}{I_1}$$

$$r_1 = bR_1 (k-1)$$

$$\frac{E_1}{E_2} = \frac{K\Phi_1 N_1}{K\Phi_2 N_2}$$

$$\frac{T_1}{T_2} = \frac{K\Phi_1 I_{a1}}{K\Phi_2 I_{a2}}$$

$$I_{ave1} = \frac{i_1 + i_2 + i_3 + \dots + i_n}{n}$$

$$I_{rms1wk} = \sqrt{\frac{i_1^2 + i_2^2 + i_3^2 + \dots + i_n^2}{n}}$$

$$f = \frac{1}{2\pi\sqrt{LC}}$$

$$f = \frac{1}{2\pi L} \sqrt{\frac{L}{C} - R^2}$$

$$P = \sqrt{3} I_L V_L \cos \phi$$

$$P_1 = V_L I_L \cos (30 - \phi)$$

$$P_2 = V_L I_L \cos (30 + \phi)$$

$$\tan \phi = \frac{\sqrt{3} (P_2 - P_1)}{(P_2 + P_1)}$$

% Voltage regulation

$$= I_1 \frac{(R_e \cos \phi \pm X_e \sin \phi)}{v_1} \times \frac{100}{1}$$

$$Z_e = \sqrt{R_e^2 + X_e^2}$$

$$\% Z_e = \frac{I Z_e}{V} \times \frac{100}{1}$$

$$S_1 = S \frac{Z_2}{Z_1 + Z_2}$$

$$E = 2,222 k_d k_p Z \Phi f$$

$$I_r = \frac{E_r}{Z_r}$$

$$E_o = V_p \frac{Z_r}{Z_s}$$

$$\cos \phi_r = \frac{R}{Z_r}$$

$$s = \frac{2\pi T (n_s - n_r)}{2\pi T n_s}$$

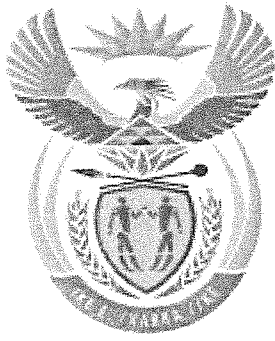
$$L = 0,05 + 0,2 \text{ Lin } \frac{d}{r}$$

$$C = \frac{1}{36 \text{ Lin } \frac{d-r}{r}}$$

$$C = \frac{1}{18 \text{ Lin } \frac{de}{r}}$$

% Regulation

$$= \frac{V_s - V_R}{V_R} \times \frac{100}{1}$$



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MARKING GUIDELINE

NATIONAL CERTIFICATE

APRIL EXAMINATION

ELECTROTECHNICS N5

7 APRIL 2015

This marking guideline consists of 9 pages.

QUESTION 1

- 1.1 Due to the resistance loss in the armature circuit, ✓ the shunt current also decreases causing a further terminal voltage drop. ✓ (2)
- 1.2 Commutating poles improve commutation. ✓ (1)
- Compensating windings minimize armature reaction. ✓ (1)
- 1.3 1.3.1 $p = 4$ $c = 2$ $Z = 800$ mech deg. = 5° and Elect deg = $p \times 5 = 20^\circ$ $I_a = 270$ A Field winding = 1600 t/p
- Demag At/p = $0.5 \times I_a / c \times Z / 2p \times (4\theta / 360)$
 $= 0,5 \times 270 / 2 \times 800 / 8 \times (4 \times 20 / 360)$ ✓ = 1500 At/p ✓
 Cross-mag At / p = $0,5 \times 270 / 2 \times 800 / 8 \times [1 - (4 \times 20 / 360)]$ ✓
 $= 5250$ At ✓ (2)
- 1.3.2 MMF = $N I$ ✓
 $I = 1500 / 1600$
 $= 0,94$ A ✓ (2)
- 1.4 1.4.1 $V = 535$ V $I_a = 40$ A $N_1 = 550$ rpm $R_a = 0,5 \Omega$ $\phi_1 = 100\%$ (1)
 $\phi_2 = 70\%$ (0,7) $T_1 = 100\%$ (1) $T_2 = 140\%$ (1,4) (2)
- $T \propto I_a \phi$
 $T_1 / T_2 = I_{a1} \phi_1 / I_{a2} \phi_2$ ✓
 $I_{a2} = T_2 I_{a1} \phi_1 / T_1 \phi_2$
 $= 1,4 \times 40 \times 1 / 1 \times 0,7$ ✓
 $= 80$ A ✓ (3)
- 1.4.2 E1 = $V - I_a R_a$
 $= 535 - (40 \times 0,5)$ ✓
 $= 515$ V ✓
- E2 = $V - I_{a2} R_a$
 $= 535 - (80 \times 0,5)$ ✓
 $= 495$ V ✓
- E1 / E2 = $N_1 \phi_1 / N_2 \phi_2$
 $N_2 = E_2 N_1 \phi_1 / E_1 \phi_2$ ✓
 $= 495 \times 550 \times 1 / 515 \times 0,7$ ✓
 $= 755,2$ r/pm ✓ (7)

[20]

QUESTION 2

$$\begin{aligned}
 2.1.1 \quad Z_A &= R - jX_c \\
 &= 8,8 - j(1/2\pi fc) \\
 &= 8,8 - j(1/2\pi 50 \times 200 \times 10^{-6}) \\
 &= 8,8 - j15,92 \\
 &= 18,19 \angle -61,07^\circ \quad \checkmark \\
 \\
 IA &= V / Z_A \\
 &= 300 \angle 0^\circ / 18,19 \angle -61,07^\circ \\
 &= 16,49 \angle 61,07^\circ \text{ A} \quad \checkmark \\
 \\
 IB &= I_T - I_A \\
 &= 25 \angle j0^\circ - 16,49 \angle 61,07^\circ \\
 &= 25 + j0 - (7,98 + j14,43) \quad \checkmark \\
 &= 17,02 - j14,43 \\
 &= 22,31 \angle -40,29^\circ \text{ A} \quad \checkmark \quad (4) \\
 \\
 2.1.2 \quad \cos \phi &= \cos 40,29^\circ \quad \checkmark \\
 &= 0,76 \text{ Lagging} \quad \checkmark \quad (2) \\
 \\
 2.1.3 \quad Z_B &= V_B / I_B \\
 &= 300 \angle 0^\circ / 22,31 \angle -40,29^\circ \quad \checkmark \\
 Z_B &= 13,45 \angle 40,29^\circ \quad \checkmark = (10,26 + j8,7) \quad (2) \\
 \\
 2.1.4 \quad X_L &= 8,7 \Omega \quad \checkmark \quad (\text{from } Z_B = 10,26 + j8,7) \quad \checkmark \quad (1) \\
 \\
 2.1.5 \quad R &= 10,26 \Omega \quad \checkmark \quad (\text{from } Z_B = 10,26 + j8,7) \quad (1)
 \end{aligned}$$

2.2

$$C_1 = 370 \times 10^{-12} \text{ for } (I_{\max})$$

$$C_2 = 340 \times 10^{-12} \text{ for } I_2 = 0,707 \text{ Im}$$

$$X_{C1} = 1 / 2\pi fc$$

$$= 10^{12} / 2\pi \times 2,5 \times 10^6 \times 370 = 172,06 \Omega \quad \checkmark$$

$$X_{L1} = X_{C1} = 172,06 \text{ resonance} \quad \checkmark$$

$$X_{L1} = 2\pi fL$$

$$L = X_L / 2\pi f = 172,06 / 2\pi \times 10^6 \times 2,5 = 10,95 \mu\text{H} \quad \checkmark$$

$$X_{C2} = 1 / 2\pi fC_2 = 10^{12} / 2\pi \times 10^6 \times 340 \times 2,5 = 187,24 \Omega \quad \checkmark$$

$$\text{Increase in } X_C = 187,24 - 172,06 = 15,18 \Omega \quad \checkmark$$

$$I_1 = V / Z_1 \quad Z_1 = R \text{ (resonance)} \quad \checkmark$$

$$I_2 = 0,707 I_1 = 0,707 V / Z_1 = V / Z_2$$

$$Z_2 = \sqrt{R^2 + (15,18)^2} \quad \checkmark$$

$$0,707 V / Z_1 = \frac{V}{Z_2}$$

$$0,707 V / R = \frac{V}{\sqrt{R^2 + (15,18)^2}} \quad \checkmark$$

$$(0,707 V)^2 / R^2 = V^2 / R^2 + (15,18)^2$$

$$[R^2 + (15,18)^2] / R^2 = V^2 / (0,707V)^2$$

$$[R^2 + (15,18)^2] / R^2 = 1 / 0,707^2$$

$$R^2 + (15,18)^2 = R^2 / 0,707^2 \quad \checkmark$$

$$0,707^2 R^2 + (0,707^2)(15,18)^2 = R^2$$

$$R^2 - 0,707^2 R^2 = (0,707^2)(15,18)^2$$

$$R^2 (1 - 0,707^2) = (0,707^2)(15,18)^2$$

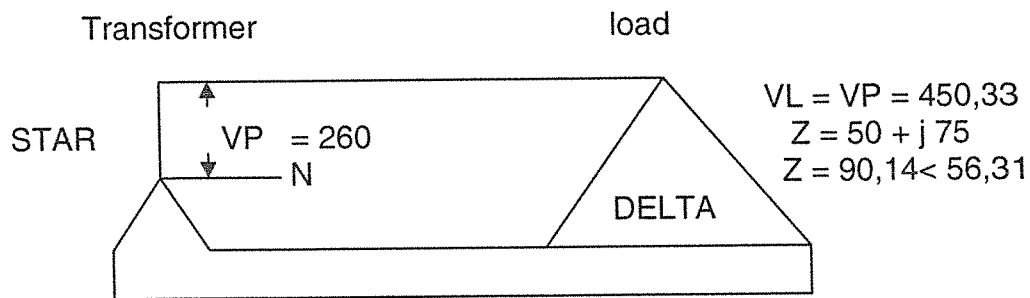
$$R^2 = (0,707^2)(15,18)^2 / (1 - 0,707^2)$$

$$R = 15,18 \Omega \quad \checkmark$$

(10)
[20]

QUESTION 3

3.1



3.1.1 $V_L = \sqrt{3} V_P = \sqrt{3} \times 260 = 450,33 \text{ V} \checkmark$ (2)
 $= V_P = 450,33 \checkmark$

3.1.2 $I_P(\text{load}) = V_P / Z_P = 450,33 < 0 / 90,14 < 56,31 \checkmark$ (2)
 $= 5 < -56,31 \checkmark$

3.1.3 $I_L = \sqrt{3} \times 5 = 8,66 \text{ A} \checkmark$ (1)

3.1.4 $P = \sqrt{3} I_L V_L \cos \phi = \sqrt{3} \times 8,66 \times 450,33 \times 0,55 \checkmark$ (2)
 $= 3,72 \text{ kW} \checkmark$

$\cos \phi = \cos 56,31$
 $\text{pf} = 0,55 \checkmark$ (1)

3.2 Single ph Trf. 15 kVA

$$V_1 / V_2 = 3500 / 700 = N_1 / N_2$$

$$R_1 = 7,5 \Omega \quad R_2 = 0,5 \Omega \quad X_1 = 15 \Omega \quad X_2 = 0,65 \Omega \quad V_1 = 3500 \text{V} \quad \cos \phi = 0,8$$

$$I_1 = V_A / V_1 = 15000 / 3500 = 4,29 \text{ A}$$

$$R_e = R_1 + R_2 (N_1 / N_2)^2 = 7,5 + 0,5(5)^2 = 20 \Omega \checkmark$$

$$X_e = X_1 + X_2 (N_1 / N_2)^2 = 15 + 0,65(5)^2 = 31,25 \Omega$$

$$Z_e = \sqrt{(R_e)^2 + (X_e)^2}$$

$$= \sqrt{(20)^2 + (31,25)^2}$$

$$= 37,1 \quad \text{OR} \quad 20 + j31,25 = 37,1 < 57,38 \checkmark$$

$$\text{REG.} = I_1 (R_e \cos \phi + X_e \sin \phi) / V_1$$

$$\begin{aligned} &= 4,29 [(20)(0,8) + (31,25)(0,6)] / 3500 \\ &= 4,29 [16 + 18,75] / 3500 \\ &= 0,043 \text{ per unit } \checkmark \end{aligned}$$

$$\text{FULL } V_2 = \text{NO LOAD } V_2 - \text{CHANGE}$$

$$\begin{aligned} &= (700) - (N/L V_2 \times \text{reg}) \\ &= 700 - (700 \times 0,043) \\ &= 700 - 30,1 \\ &= 669,9 \text{ V } \checkmark \end{aligned}$$

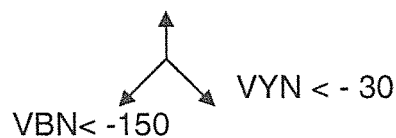
(4)

3.3 3.3.1 3 PH. Star con motor $V_L = 500\text{V}$ $P_{\text{out}} = 100 \text{ kW}$ $\eta = 0,8$
 $\text{COS } \phi = 0,8$
 $P_{\text{in}} = 100 / 0,8$
 $= 125 \text{ kW}$
 $P = \sqrt{3} I_L V_L \text{COS } \phi$
 $125\,000 = \sqrt{3} I_L (500) (0,8) \checkmark$
 $I_L = 180,42 \text{ A } \checkmark$

FOR DELTA CON. MOTOR WINDING :

$$\begin{aligned} I_L &= \sqrt{3} I_P = \sqrt{3} 180,42 = 312,5 \checkmark \\ P &= \sqrt{3} I_L V_L \text{COS } \phi \\ 125\,000 &= \sqrt{3} \times 312,5 \times V \times 0,8 \\ V_L &= 288,68 \text{ V } \checkmark \end{aligned}$$

$$V_{RN} < 90$$



$$V_p = 380$$

3.4 3.4.1 Correctly connected

$$\begin{aligned} V_{RY} &= V_{RN} + V_{NY} && \text{OR} \\ &= 380 \angle 90 + 380 \angle 150 && 380 \times \sqrt{3} = 658,18,54 \\ &= (0 + j 380) + (-329 + j 190) \checkmark \\ &= -329 + j 570 \\ &= 658,13 \angle 120 \\ V_{RY} &= V_{BR} = V_{YB} = 658,13 \checkmark \end{aligned}$$

With one phase reversed

$$\begin{aligned}
 V_{RY} &= 380 \angle 0^\circ + 380 \angle -120^\circ \\
 &= (380 - j0) + (-190 - j329,09) \quad \checkmark \\
 &= 190 - j329,09 \\
 &= 380 \angle -60^\circ \quad \checkmark
 \end{aligned}$$

(8)
[20]

QUESTION 4

4.1

$$\begin{aligned}
 d_1 &= 125 \times 10^{-2} & \text{dia} &= 0,6 \text{ cm} & r &= 0,3 \times 10^{-2} \text{ m} \\
 d_2 &= 165 \times 10^{-2} \\
 d_3 &= 235 \times 10^{-2}
 \end{aligned}$$

$$\begin{aligned}
 d_e &= \sqrt[3]{1,25 \times 1,65 \times 2,35} \quad \checkmark \\
 &= 1,69 \text{ m} \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 L &= \text{km} [0,05 + 0,2 \log_e (d_e/r)] \text{ mH} \\
 &= 35 [0,05 + 0,2 \log_e (1,69 / 0,003)] \text{ mH} \quad \checkmark \\
 &= 46,09 \text{ mH} \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 C &= 35 [1 / 18 \log_e (1,69 / 0,003)] \quad \checkmark \\
 &= 0,307 \mu\text{f} \quad \checkmark
 \end{aligned}
 \tag{6}$$

4.2

4.2.1

$$\begin{aligned}
 R &= 22 \text{ ohms} & X &= 30 \text{ ohms} \\
 P &= 2200 \text{ kW} & V_r &= 31 \text{ kV} & \cos \phi &= 0,85 = 31,79
 \end{aligned}$$

$$\begin{aligned}
 I &= P / V \cos \phi \\
 &= 2200000 / 31000 \times 0,85 \\
 &= 83,49 \text{ A} \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 V_s &= V \angle \phi + IR + IX \angle 90^\circ \\
 &= 31000 \angle 31,87^\circ + 83,49 \times 22 + 83,49 \times X \\
 30 &< 90 \quad \checkmark \\
 2504,7 & \\
 &= 28163,48 + j 18872,5 \quad \checkmark \\
 &= 33902,1 \angle 33,83 \text{ kV} \quad \checkmark
 \end{aligned}
 \tag{4}$$

4.2.2

Reg

$$\begin{aligned}
 &= V_s - V_r / V_r \\
 &= 33902 - 31000 / 31000 \quad \checkmark \\
 &= 0,094 \quad \checkmark
 \end{aligned}
 \tag{2}$$

$$\begin{aligned} \eta &= P_o / P_o + \text{Losses} \\ \eta &= 2200 / \frac{2200 + 83,49^2 \times 22}{1000} \checkmark \\ &= 93,4 \% \quad \checkmark \end{aligned} \tag{2}$$

4.3 $Z = 5 + j6 = 7,81 \angle 50,19$ $V_L = 400V$ $\phi = 50,19 \text{ lag}$
 $V_p = 400 / \sqrt{3}$
 $= 242,49 V \quad \checkmark$
 $I_P = V_P / Z_P$
 $= 230,9 \angle 0 / 7,81 \angle 50,19$
 $= 29,56 \angle -50,19 \quad \checkmark$

$I_L = I_P = 29,56 \angle -50,19 \quad \checkmark$

$P_2 + P_1 = \sqrt{3} V_L I_L \cos \phi$
 $= \sqrt{3} \times 400 \times 29,56 \cos 50,19$
 $= 13,112 \text{ kW} \dots\dots\dots (1)$

$\tan \phi = \sqrt{3} (P_2 - P_1) / P_2 + P_1$
 $P_2 - P_1 = \tan 50,19 \times 13,112 / \sqrt{3} \quad \checkmark$
 $= 9,08 \text{ kW} \dots\dots\dots (2)$

$2 P_1 = 4,03 \dots\dots\dots (1 - 2)$
 $P_1 = 2,02 \text{ kW} \quad \checkmark$
 $P_2 = 13,112 - 2,02$
 $= 11,092 \text{ kW} \quad \checkmark$

(6)
[20]

QUESTION 5

5.1 $P_o = 650 \text{ kW}$ $V = 3800 V$ $\eta = 85 \% (0,85)$ $\cos \phi = 0,8$

$P_{in} = P_{out} / \eta$
 $= 650000 / 0,85 \quad \checkmark$
 $= 764705,88 W \quad \checkmark$

$I_L = P_{in} / \sqrt{3} V_L \cos \phi$
 $= 764705,88 / \sqrt{3} \times 3800 \times 0,8 \quad \checkmark$
 $= 145,23 A$

$I(\text{alt}) = 145,23 A \quad \checkmark$

$I(\text{motor}) = I_L / \sqrt{3}$
 $= 145,23 / \sqrt{3}$
 $= 83,85 A \quad \checkmark$

$S = \sqrt{3} V_L I_L$
 $= \sqrt{3} \times 3800 \times 145,23 \quad \checkmark$
 $= 955873,81 VA$
 $= 955,87 KVA \quad \checkmark$

(7)

5.2 5.2.1 $f = 50 \text{ Hz}$ $p = 4/2 = 2$ $N_r = 1000 \text{ rpm}$ $T = 170 \text{ Nm}$

$$\begin{aligned} f &= N_s / 60 \\ \therefore N_s &= 60 \times f / p \quad \checkmark \\ &= 60 \times 50 / 2 \\ &= 1500 \text{ rpm} \quad \checkmark \end{aligned}$$

Rotor input

$$\begin{aligned} P &= 2 \pi N_s T / 60 \\ &= 2 \pi \times 1500 \times 170 / 60 \quad \checkmark \\ &= 26703,5 \text{ W} \\ &= 26,7 \text{ kW} \quad \checkmark \end{aligned} \quad (4)$$

5.2.2 Rotor Cu Loss = $S \times$ Rotor input

$$\begin{aligned} S &= N_s - N_r / N_s &= 1500 - 1000 / 1500 \quad \checkmark \\ & &= 0,33 \quad \checkmark \\ \text{Rotor Cu Loss} & &= 0,33 \times 26703,5 \\ & &= 8812,2 \text{ W} \quad \checkmark \end{aligned} \quad (3)$$

5.3 $f = 50 \text{ Hz}$ $\phi = 0,3 \text{ wb}$ $k_d = 0,96$ $N = 360 \text{ rpm}$

$$\begin{aligned} V_L & &= \sqrt{3} V_p \\ V_p & &= 20 / \sqrt{3} \\ & &= 11,557 \text{ kV} \quad \checkmark \end{aligned}$$

$$\begin{aligned} V_p & &= 2 k_f k_d k_p \phi f X \\ X & &= V_p / 2 k_f k_d \phi \\ & &= 11547 / 2 \times 1,11 \times 0,96 \times 1 \times 0,3 \times 50 \quad \checkmark \\ & &= 361,2 \text{ conductors / ph (say 362)} \\ f & &= N_p / 60 \\ p & &= 60 f / N \\ & &= 60 \times 50 / 375 \\ & &= 8 \text{ pole pairs} \\ & &= 16 \text{ poles} \quad \checkmark \end{aligned}$$

$$\begin{aligned} \text{Slots / phase} & &= 60 \text{ slots / phase} \quad \checkmark \\ 3 \times 20 \text{ slots / phase} & & \end{aligned}$$

$$\begin{aligned} \text{Cond / Slot} & &= (\text{cond. / ph}) / (\text{slots / ph}) \\ & &= 362 / 60 \\ & &= 6,03 \quad \checkmark \end{aligned} \quad (6)$$

[20]

TOTAL: 100